Figure 8 Images acquired by the system during tracking of the real stimulus. Left/right camera images, when the object is close (A/B), when the object is far (D/E). A pseudo-color image showing the normalized squared peak responses $R_c(x, y, \Delta c)$ for the three populations at each location $(x, y)$ in the right eye image, when the object is close (C), when the object is far (F). The red/green/blue intensities are proportional to the responses for $\Delta c = 4/0/-4$ (near/fixation/far disparities).